Sustainable mobility by seamless digitalization



Autonomous Conference, Vienna 29.09.2021 14:15-16:15 **T**[[ech



Input from Europe's Funded Electromobility research projects

Today's contradictions

Reiner John, AVL List, Austria et. all

Presentation V1.0

Emergence: the solution comes from system



Trustfully Collaboration in complex, complicated and chaotic systems

Sustainable Mobility and climate neutral economy by emergence

Driving, connected assets, digital twin Resources, Design, Manufacturing End of life vehicle in traffic: intrinsic vs. extrinsic efficiency, intelligence local far Power plant **Power Distribution** HITH Hofburg Wier components and data for cyclic economy

ECO Design, Carbon dept visibility, environment impact, supply chain resources, Efficiency, Material substitution, reduce yield losses

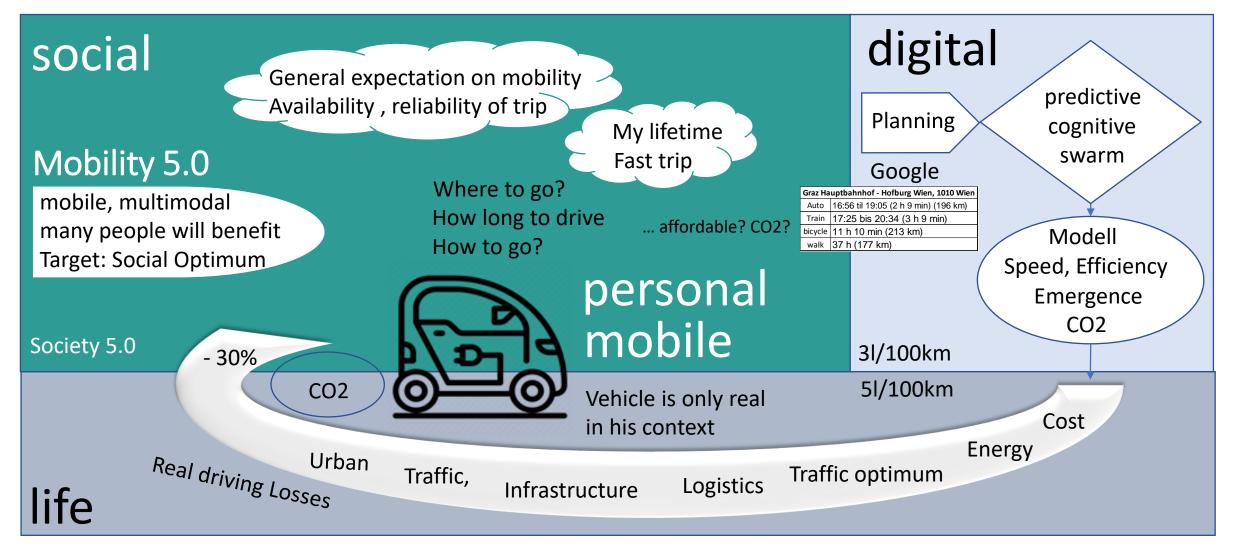
Product as a service, advisory service, Integration and simulation of energy grid, traffic with real time energy prediction, maximize lifetime, predictive maintenance

Simple System complicated System complexe System chaotic System Cynefin-Framework

Design for recycling, Re-Use Separability and 2nd life or Re-attribute, product disassembly

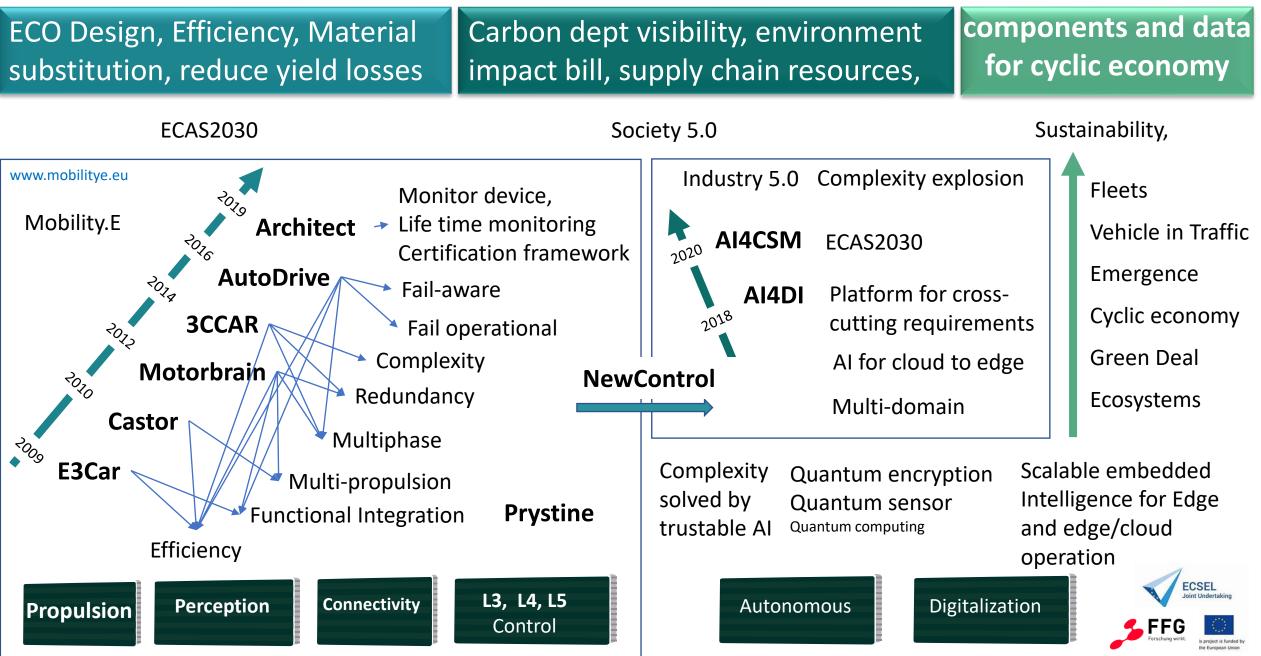
Driving, connected assets, digital twin

The individual human will choose his way of mobility, technology will minimize emissions, optimized by extrinsic intelligence and efficiency from electric, connected, automated and shared mobility



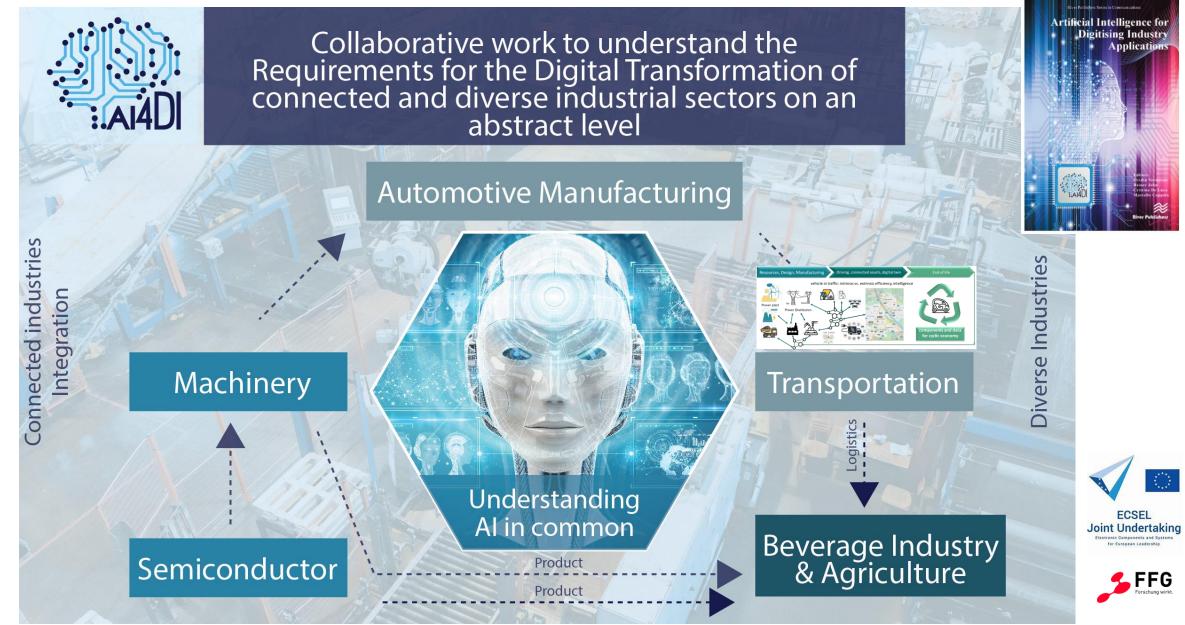
Industry 5.0 and Society 5.0: fair use of resources in the sense of a social optimum for the needs of all people in the society.

The ECO system of European funded projects



AI4DI artificial intelligence for the digitizing industry

AI4DI Book for download https://we.tl/t-6ZDubJZIfN



Build and sustain dynamic AI technology ecosystems in Europe, ensuring ethical, responsible, and trusted AI for safety-critical real-time applications.







Holistic virtualized platforms

enabling mobility as a service

Integrated, Fail-Operational, Cognitive Perception, Planning and **Control Systems for Highly Automated Vehicles**



Increase the accuracy and robustness of algorithms, E/E architectures for adaptive perception



Increase performance, power, reliability, and reduce cost of the onboard computing platforms used for perception, cognition and control



Achieve certifiability of adaptive algorithms for safety-critical control functions



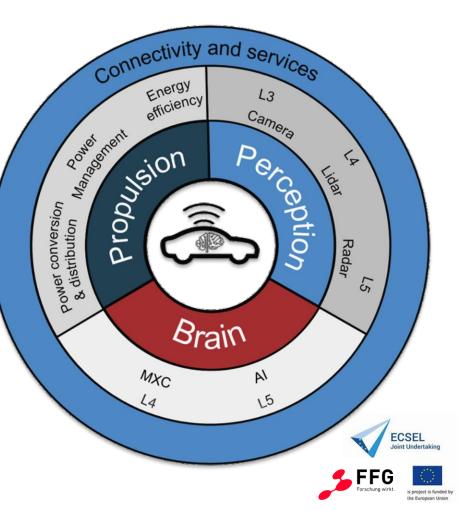
Develop a generalized hardware abstraction layer for efficient, adaptive fail-operational control of propulsion systems across vehicular platforms

Competitive edge to European industry





Increase user acceptance of automated control functions



European funded projects & technologies Auto Dri ?e



MOBILITY>E LIGHTHOUSE

SAE L5: fail operational propulsion





E-Axle: What's new?

Driving

fail-operational design by using clutches to be able to de-couple in case of mech. failures scalable design for faster lightweight robo taxis (1000 kg, 100 km/h) & more heavy shuttle pods (3000 kg, 30 km/h)



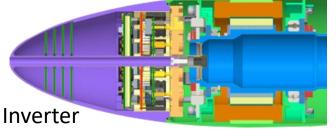
AIRCRAFT

OF THE LANGE RESEARCH AIRCRAFT

V AVIATION INVENTOR

DEVELOPMENT OF CONTROL ALGORITHMS FOR THE INVENTOR

UTM5 FAIL-OPERATIONAL AVIATION BATTERY MONITORI



Lange Aviation

Germany

& Battery Monitoring for Aerial Vehicle

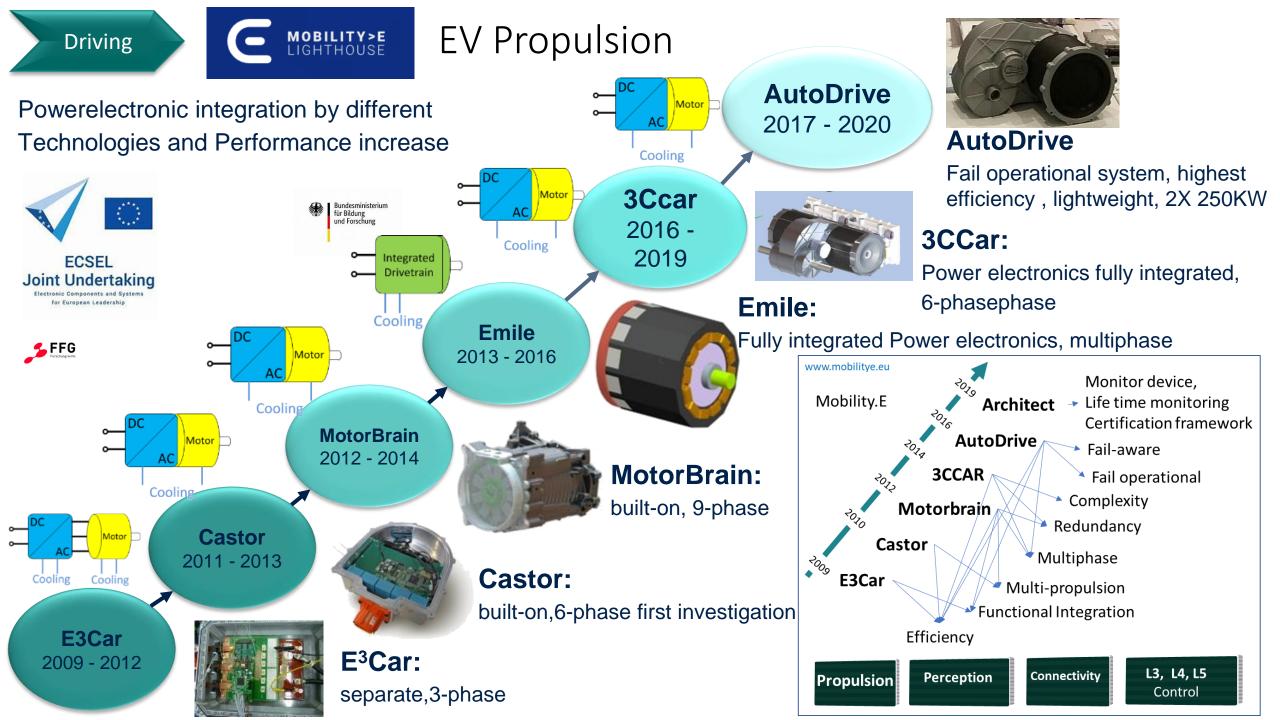
https://www.mobilitye.eu/projects/autodrive

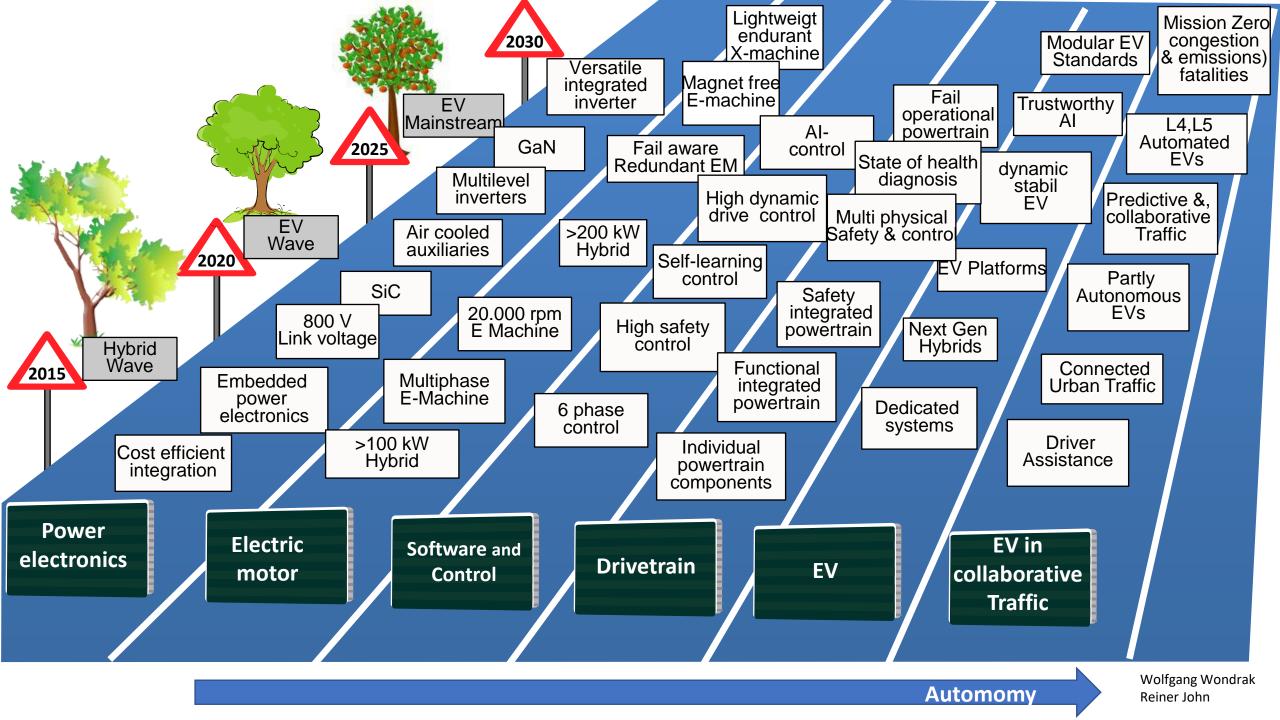


SAE L4: driving from harbor to city of Malaga Iriza, Technalia et. all AutoDrive – technologies to be safe

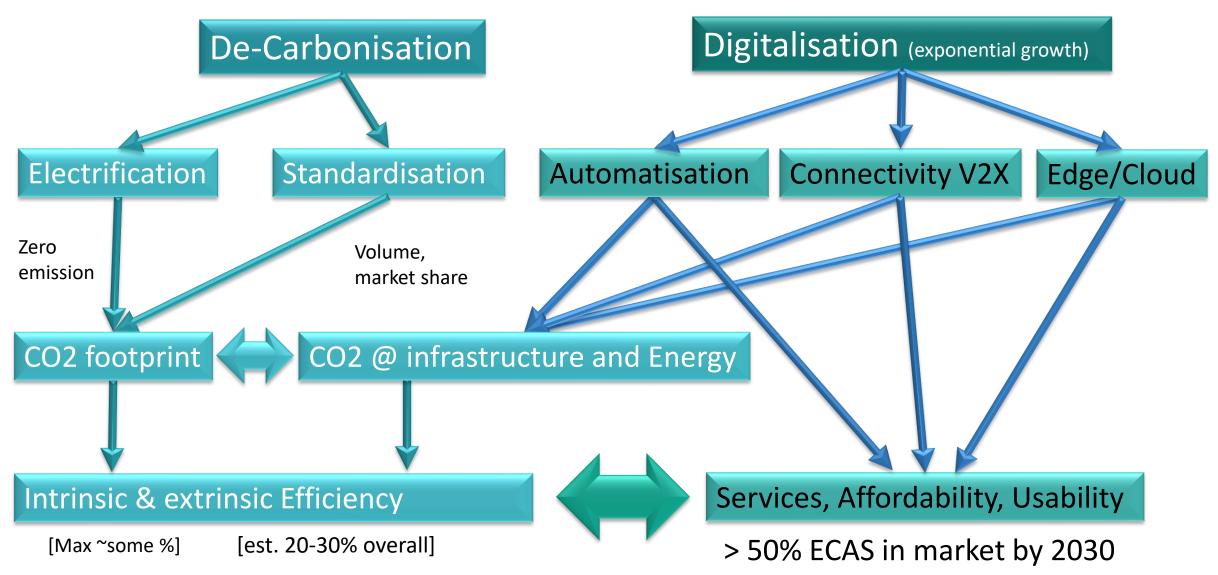


Flying mission on the ice seanttps://autodrive-project





Semantic – Layer ECAS





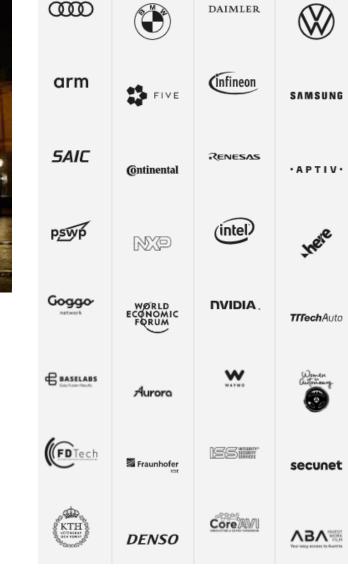


ΤΓΓech

ECSEL Joint Undertaking

s project is funded b

Final page: Thank you very much, Many greetings to Vienna Autonomous 2021



DAIMLER

